

## The isochronism problem

Consider the 1D physical system

$$m\ddot{x} = -\frac{dU}{dx}.$$

For which  $U$  is the system **isochronic** ?

The **harmonic potential**  $U(x) = \frac{1}{2}kx^2$  is one solution.

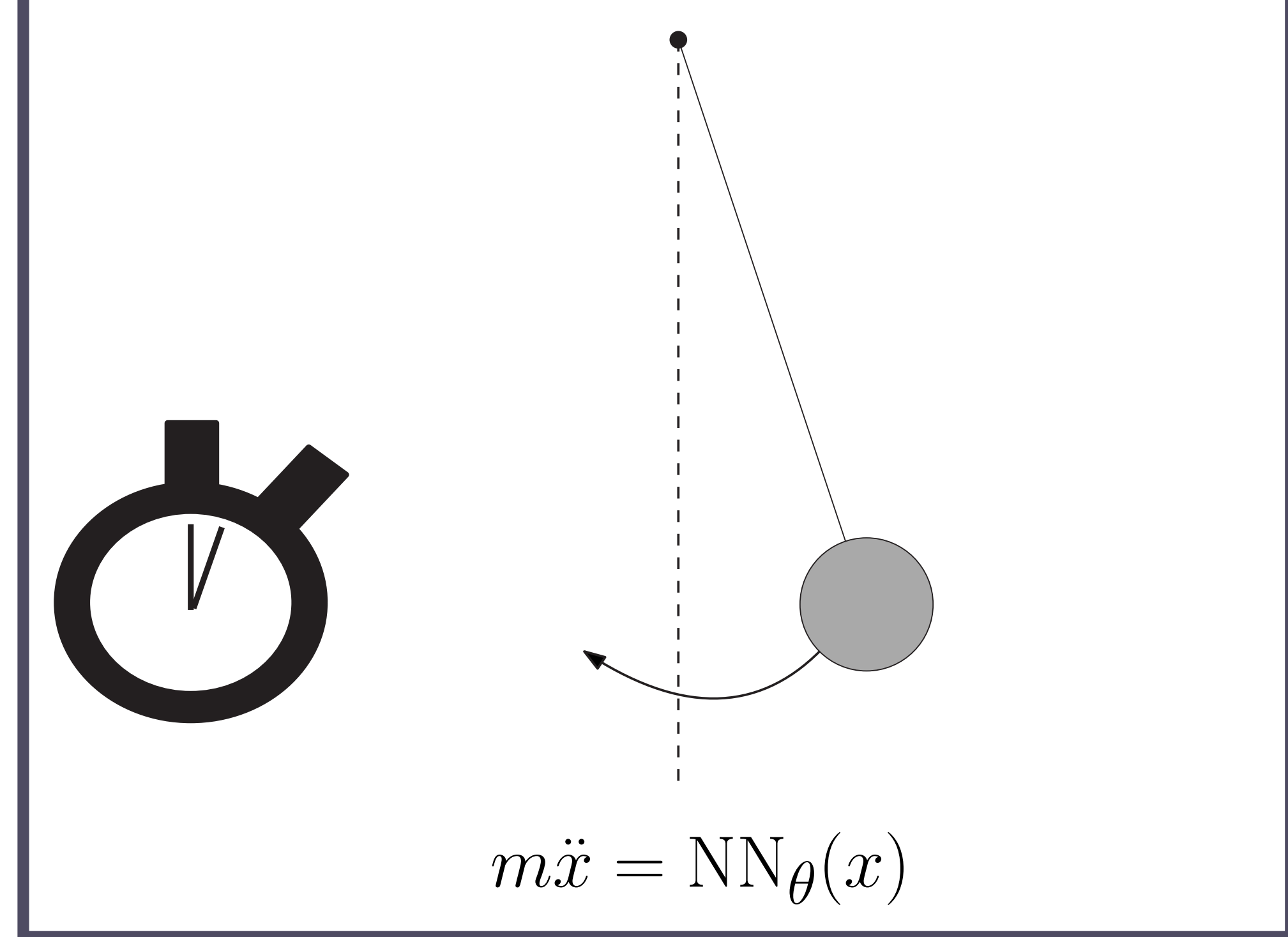
**Question** : are there other such symmetric functions  $U$  ?

**Answer** : no, necessarily  $U(x) \propto x^2$ .

## Approach

We retrieve this uniqueness result **experimentally** with deep learning.

- Parametrize the unknown force field by a neural network.
- Impose periodicity with a loss on the trajectories.
- Train the neural differential equation.
- Compare the obtained phase portrait with that of the harmonic oscillator.

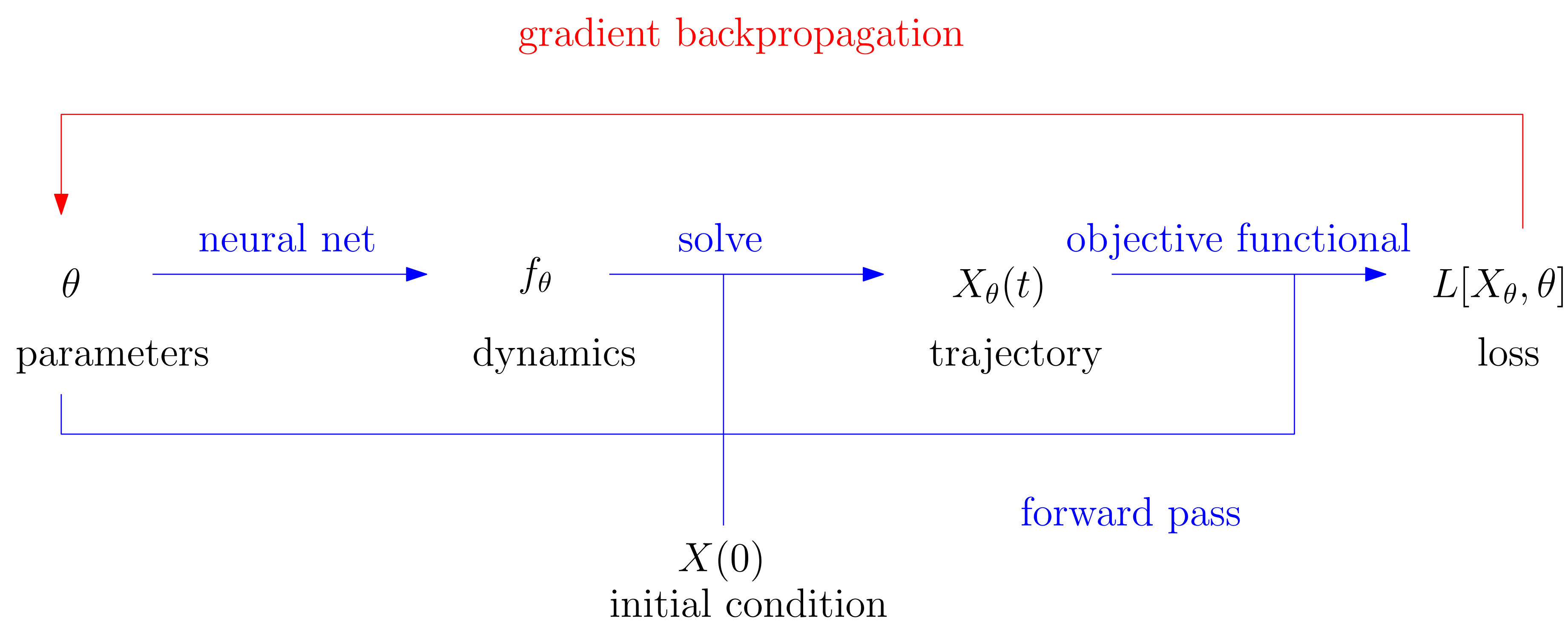


## Neural differential equations

Neural differential equations parametrize the flow of an ODE by a neural net :  $\frac{dX}{dt} = f_\theta(X)$ .

Given some loss  $L[X_\theta, \theta]$ , the gradient is backpropagated through the ODE [Chen *et al.*, 2018].

▷ Learn a flow by imposing a loss on its trajectories.



## Experiment

- Parametrize the dynamics

$$m\ddot{x} = f_\theta(x),$$

where  $f_\theta(x)$  is a neural network approximating the force field  $f(x) = -dU/dx$ .

- Measure the **periodicity discrepancy** with the loss

$$L[X_\theta] = \|X_\theta(T) - X_\theta(0)\|^2.$$

- Optimize

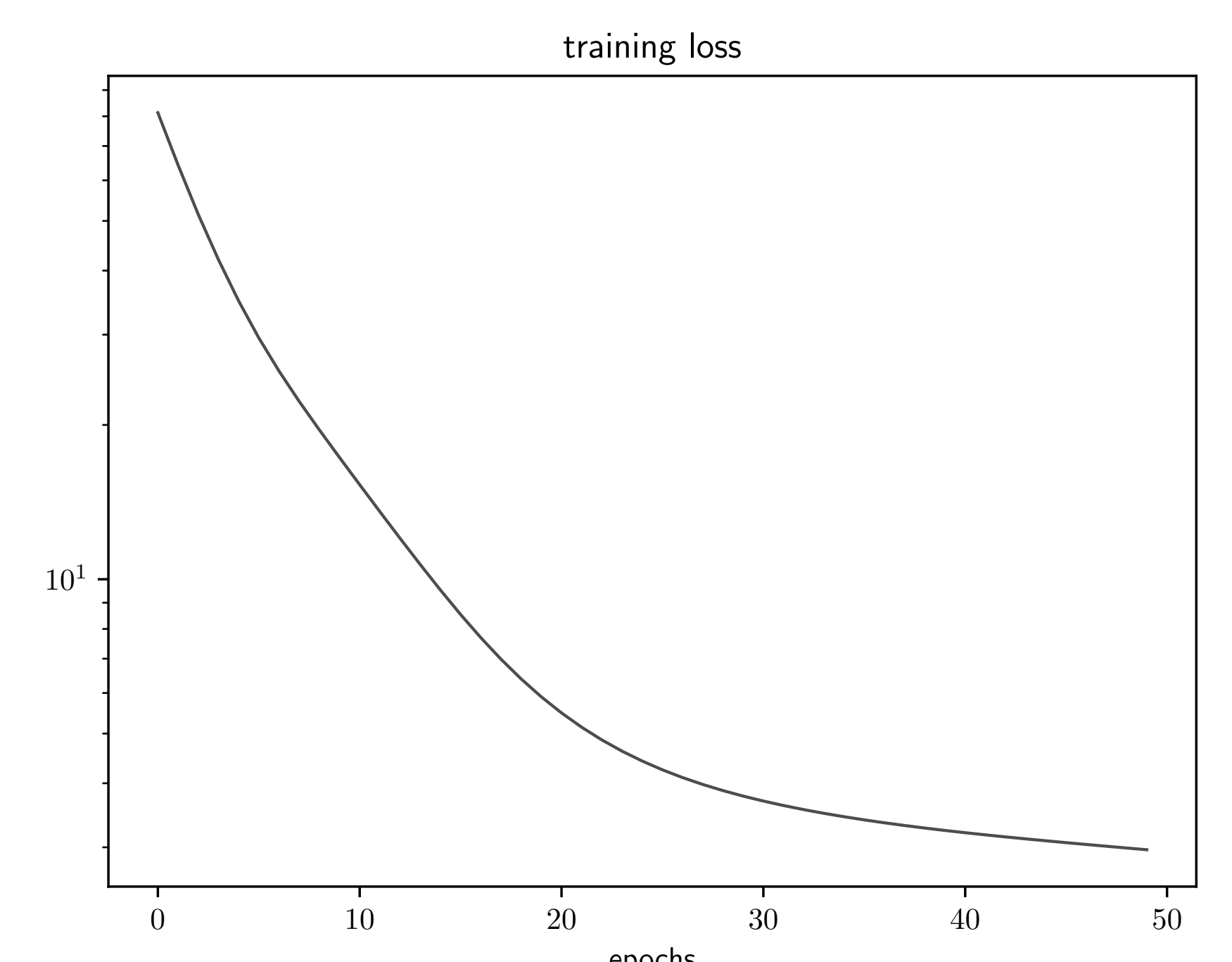
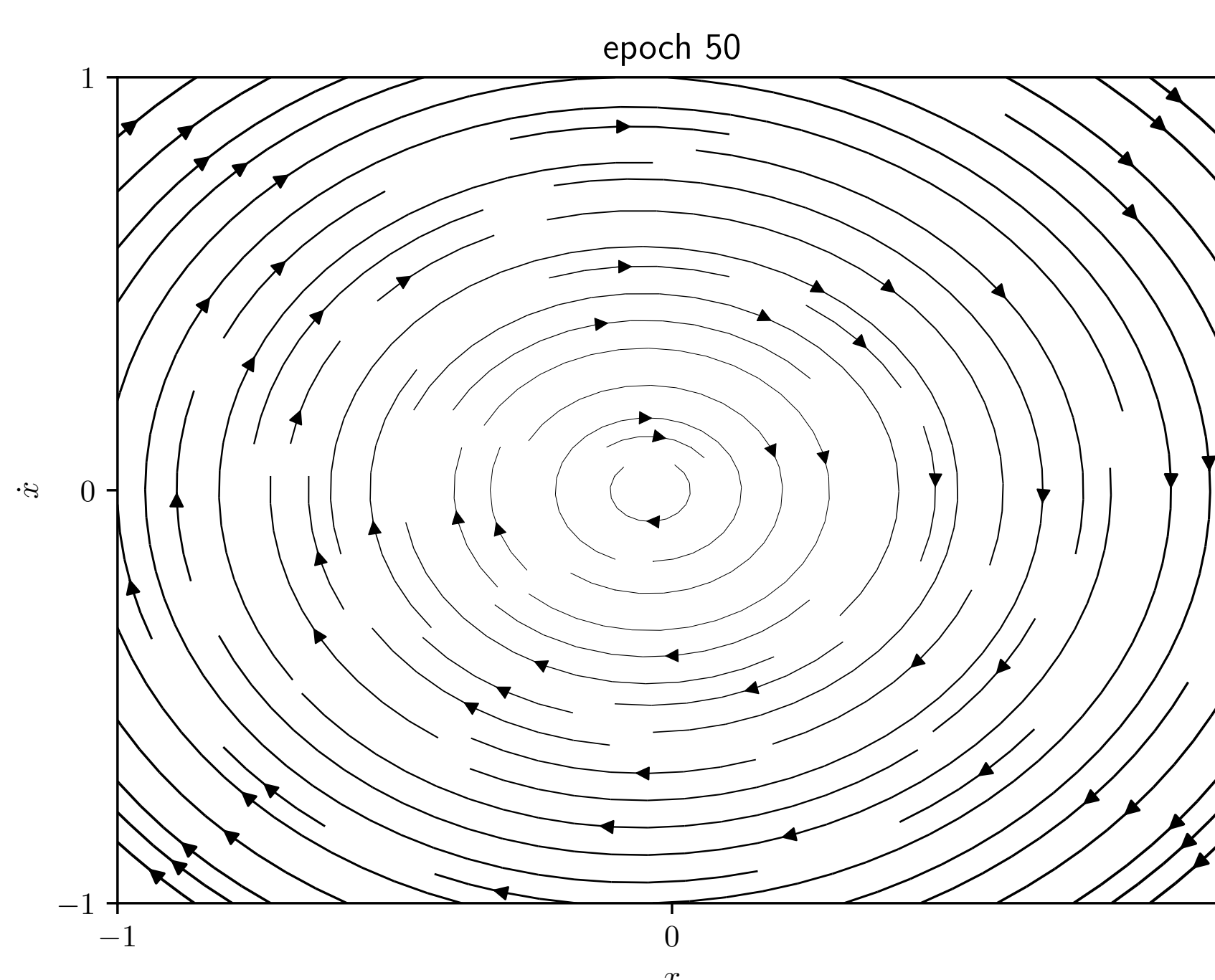
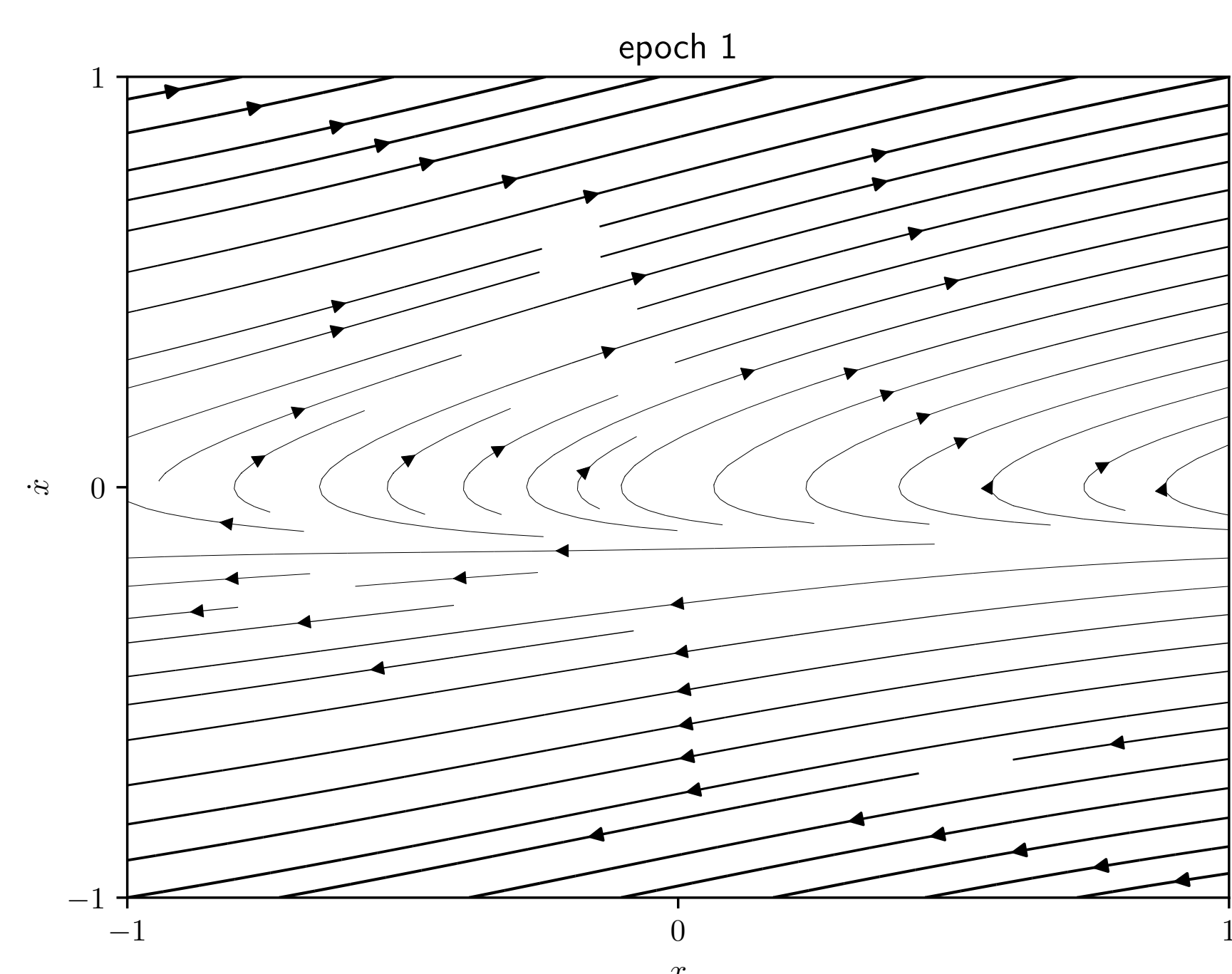
$$\min_\theta L[X_\theta]$$

by gradient descent through the ODE, with random initial conditions

$$X(0) \sim \mathcal{N}(0, I).$$

We trained the loss  $N = 100$  training points with  $T = 2\pi$ . We took for  $f_\theta$  a 2-layer fully connected architecture with width 16 and tanh nonlinearity.

## Results



After training, the trajectories in the phase space are circular, meaning that the obtained neural potential is quadratic :  $U(x) = \frac{1}{2}m\omega^2x^2$ , with  $\omega = 2\pi/T$ .

## Theoretical derivation

Inspired from [Osypowski & Olsson, 1986]

- For some energy  $E$ , let  $y(E)$  denote the amplitude :  $-y(E) \leq x \leq y(E)$ .
- Write the period in terms of the energy :  $T = 2\sqrt{2} \int_0^{y(E)} \frac{dx}{\sqrt{E - U(x)}}$ .
- Changing variables,  $T = 2\sqrt{2} \int_0^1 g(uE) \frac{du}{\sqrt{u(1-u)}}$  with  $g(U) = x'(uE)\sqrt{uE}$ .
- This integral is a constant with respect to  $E$ , implying that  $g$  is a constant, and hence  $U(x) \propto x^2$ .

## Conclusion

We recovered a result from elementary theoretical mechanics using neural differential equations.

▷ The training loss is implicitly defined in terms of the neural net. This is an example of **implicit layer**.

▷ It would be interesting to extend this type of approach to other fields, replacing time translation with other symmetries.